

Visibility and shadows

Why visibility?

- projecting 3D objects into 2D not enough
- depth has to be considered (the 3rd D)



How do we solve visibility?

- Remember raytracing?
- All objects evaluated at the same time



Visibility in other methods

- Remember local \rightarrow world \rightarrow camera
- Each object treated separately (locally)
 - i.e. we need to take care of the depth ourselves, unlike raytracing
 - moreover, one object has many separate faces!



Optimizing visibility

• Get rid of objects that are surely not visible

- Frustum culling
- Backface culling
- Occlusion culling

Frustum culling

- 6 planes
 - Inside = visible volume
- Is a point is inside?
- Object bounding box
 - Speed up

FAR

RIGHT

NEAR

Occlusion culling

- Some objects are fully occluded by others
- Spatial relations between objects
- Portals, occlusion culling
- Realtime rendering

Backface culling

- Which object faces are visible?
- Remember normal vector (face orientation)



Multiple objects

 Let's consider polygonal objects => reduce the object visibility into faces visibility



Main concept – consider object depth (z)

Remember world \rightarrow camera



Painter's algorithm

Sort faces in a back-to-front order, render



 New pixels overwrite old pixels



Painter's algorithm problems

- which vertex represents a face?
- intersecting faces
- cyclically overlapping faces



redundant rendering



Other algorithms

- Warnock algorithm
 - subdivide screen into a quadtree until whole cell empty or whole cell inside polygons
- Reversed painter's algorithm
 - paint front-to-back and paint only empty areas
- Z-buffer
 - remember z-value for each pixel and only paint when new z is higher

Z-buffer

- works in screen space
- screen w×h \leftrightarrow z-buffer w×h
- for each $0 \le x \le w, 0 \le y \le h$: z-buffer[x,y] $\leftarrow z_{min}$ for each face: rasterize it into pixels {x,y,z} for each face's pixel (x,y,z): if z > z-buffer[x,y] then : $z-buffer[x,y] \leftarrow z$ and screen $[x, y] \leftarrow$ face color

Z-buffer pros and cons

- GPU support
- precision issues might occur
- z-buffer test before per-pixel-lighting or pixel shading saves a lot of redundant work
- memory demands (width × height × precision)
 - can be reduced by scanline (width×1×precision)

Lights, visibility, texture...



What's missing is shadows





Shadows

Why shadows?



Shadows in global methods

raytracing





radiosity

Graphical systems, visualization and multimedia

Raytraced shadows

- Camera→pixel→ray→intersection←object
- Intersection→shadow ray→light(s)
- Test shadow ray for object intersections
 - shadow if true
 - light if false



Radiosity shadows

- Are created naturally without special effort
- Mutually occluded areas have low form factor



Shadows in local methods

Shadow volumes

geometry space

REALTIME

Shadow maps screen space

Shadow maps

z-buffer analogy

look from the light

- "render" the scene and store depth information in a shadow map
 - 2D raster data
 - smallest distance between light and objects

Shadow maps

- For a polygon pixel to be rendered
- Find its position in the light's projection plane → (x,y,z)



If z > shadow map [x,y] then shadow

Shadow maps pros & cons

- memory consumption
 - 1 light = 1 shadow map
 - high resolution necessary
- aliasing
 - use high resolution
 - filtering necessary
- smooth (soft) shadows
 when filtered



- imprecise due to z-buffer quantization
- light-specific transformation

Shadow mapping example



http://www.nealen.net/projects/ibr/shadows.pdf

Shadow map resolution

 How many points are stored in the 2D shadow map

 Low counts = shadow artifacts



Stamminger, Drettakis: Perspective Shadow Maps

Filtering and soft shadows

- Removes artifacts (jagged edges)
- Simulates soft shadows



Soft-Edged Shadows, http://www.gamedev.net

Graphical systems, visualization and multimedia

Shadow volume

 create dummy geometry object extending each object in the direction of the light

shadow volume

 when displaying an object to a pixel (x,y,z), test if (x,y,z) is inside/outside the shadow volume

Shadow volume



Pseudo-code

1. Compute ambient light for whole scene and update z-buffer along with that

2. Which screen areas are in shadow?

- 3. For all areas outside the shadow:
 - 4. Compute diffuse and specular light components
- 5. Iterate for all lights

Shadow volume pros & cons

- hard shadows
 - modifications for soft shadows necessary
- GPU implementation using stencil buffer
- high complexity for high-polygon models
- what if camera is inside the shadow volume?
- shadow volumes expensive on CPU
 - now vertex shaders

Shadows vs. light types

- Directional (parallel) light
 - easy shadow maps and shadow volumes
- Spot light
 - shadow map by perspective transformation
 - easy shadow volume
- Omni light
 - shadow map hard
 - easy shadow volume (same as spotlight)
- Area light
 - approximate by multiple lights



Summary

Camera, object, scene

- Local, world (global), camera coordinates
- Transformations (in 2D & 3D)
- Matrix operations
 - translate, rotate, scale
 - projections
 (orthogonal, perspective)
- Object representation
 - boundary, volume, polygonal parametric, implicit, F-rep



Rasterization, Visibility

- Line and polygon rasterization
- Linear interpolation
- Antialiasing

- Visible volume
- Backface culling
- Painter's algorithm
- Z-Buffer



Texture

- Texture coordinates, texture mapping
- Texture filtering
 - Bilinear interpolation
 - Nearest neighbor



Lighting

- Light types
- Lighting models and illumination techniques
 - local, global
 - empiric, physical
- Shading models

 flat, Gouraud, Phong
- Raytracing, radiosity





Shadows

- Shadow generation in global illumination
- Shadow generation in local models
- Stencil shadows (shadow volume)
- Shadow maps
- Soft shadows

